

7.3: Translation and Partial Fractions

Let us refresh ourselves on the rules of **partial fraction decomposition**. For the next two rules let

$$R(s) = \frac{P(s)}{Q(s)}$$

where $P(s)$ is a polynomial of degree less than that of $Q(s)$.

Rule 1. (Linear Factor Partial Fractions)

The portions of the partial fraction decomposition of $R(s)$ corresponding to the linear factor $s - a$ of multiplicity n is a sum of n partial fractions, having the form

$$\frac{A_1}{s - a} + \frac{A_2}{(s - a)^2} + \cdots + \frac{A_n}{(s - a)^n}$$

where A_1, A_2, \dots, A_n are constants.

Rule 2. (Quadratic Factor Partial Fractions)

The portions of the partial fraction decomposition of $R(s)$ corresponding to the quadratic factor $(s - a)^2 + b^2$ of multiplicity n is a sum of n partial fractions, having the form

$$\frac{A_1s + B_1}{(s - a)^2 + b^2} + \frac{A_2s + B_2}{((s - a)^2 + b^2)^2} + \cdots + \frac{A_ns + B_n}{((s - a)^2 + b^2)^n}$$

where $A_1, A_2, \dots, A_n, B_1, B_2, \dots, B_n$ are constants.

Theorem 1. (Translation of the s -Axis)

If $F(s) = \mathcal{L}\{f(t)\}$ exists for $s > c$, then $\mathcal{L}\{e^{at}f(t)\}$ exists for $s > a + c$, and

$$\mathcal{L}\{e^{at}f(t)\} = F(s - a).$$

Equivalently,

$$\mathcal{L}^{-1}\{F(s - a)\} = e^{at}f(t).$$

Thus the translation $s \rightarrow s - a$ in the transform (s -axis) corresponds to multiplication of the original function of t by e^{at} .

Example 1. Find $\mathcal{L}\{e^{at}t^n\}$, $\mathcal{L}\{e^{at} \cos kt\}$ and $\mathcal{L}\{e^{at} \sin kt\}$.

$$\mathcal{L}\{t^n\} = \frac{n!}{s^{n+1}} \rightarrow \int_0^\infty \quad \mathcal{L}\{e^{at}t^n\} = \frac{n!}{(s-a)^{n+1}}$$

$$\mathcal{L}\{\cos kt\} = \frac{s}{s^2+k^2} \rightarrow \int_0^\infty \quad \mathcal{L}\{e^{at} \cos kt\} = \frac{s-a}{(s-a)^2+k^2}$$

$$\mathcal{L}\{\sin kt\} = \frac{k}{s^2+k^2} \rightarrow \int_0^\infty \quad \mathcal{L}\{e^{at} \sin kt\} = \frac{k}{(s-a)^2+k^2}$$

Example 2. Consider a mass-and-spring system with $m = \frac{1}{2}$, $k = 17$ and $c = 3$ which gives the equation

$$x'' + 6x' + 34x = 0.$$

If the mass is set into motion with $x(0) = 3$ and $x'(0) = 1$, find the resulting damped free oscillations.

$$\begin{aligned} \mathcal{L}\{x'' + 6x' + 34x\} &= \mathcal{L}\{0\} \\ 0 &= (s^2X - 3s - 1) + 6(sX - 3) + 34X \\ X &= \frac{3s + 19}{s^2 + 6s + 34} = 3 \cdot \frac{s+3}{(s+3)^2 + 25} + 2 \cdot \frac{5}{(s+3)^2 + 25} \end{aligned}$$

Thus
 $X = \mathcal{L}^{-1}\{X\} = e^{-3t}(3\cos 5t + 2\sin 5t)$

Example 3. Find the inverse Laplace transform of

$$R(s) = \frac{s^2 + 1}{s^3 - 2s^2 - 8s}.$$

$$\frac{s^2 + 1}{s^3 - 2s^2 - 8s} = \frac{A}{s} + \frac{B}{s+2} + \frac{C}{s-4} = -\frac{1}{8} + \frac{5}{12} + \frac{17}{24}$$

$$\text{So } \mathcal{L}^{-1}\{R(s)\} = -\frac{1}{8} + \frac{5}{12}e^{-2t} + \frac{17}{24}e^{4t}.$$

Example 4. Solve the initial value problem

$$y'' + 4y' + 4y = t^2; \quad y(0) = y'(0) = 0.$$

$$\mathcal{L}\{y'' + 4y' + 4y\} = \mathcal{L}\{t^2\} \quad \text{So that}$$

$$\frac{2}{s^3} = s^2Y + 4sY + 4Y$$

$$Y = \frac{1}{4}t^2 - \frac{1}{2}t + \frac{3}{8} - \frac{1}{4}te^{-2t} - \frac{3}{8}e^{-2t}$$

$$Y = \frac{2}{s^3(s+2)^2} = \frac{A}{s^3} + \frac{B}{s^2} + \frac{C}{s} + \frac{D}{(s+2)^2} + \frac{E}{s+2}$$

$$A = \frac{1}{2}, B = -\frac{1}{2}, C = \frac{3}{8}, D = -\frac{1}{4}, E = -\frac{3}{8}$$

Exercise 1. Solve the damped and forced mass-spring-dashpot system given by

$$x'' + 6x' + 34x = 30 \sin 2t; \quad x(0) = x'(0) = 0.$$

$$\mathcal{L}\{x'' + 6x' + 34x\} = \mathcal{L}\{30 \sin 2t\}$$

$$\frac{60}{s^2 + 4} = s^2 X + 6sX + 34X$$

So

$$X = \frac{60}{(s^2 + 4)(s^2 + 6s + 34)} = \frac{As + B}{s^2 + 4} + \frac{Cs + D}{(s + 3)^2 + 25}$$

$$X = \frac{5}{29} (-2 \cos 2t + 5 \sin 2t)$$

$$+ \frac{2}{29} e^{-3t} (5 \cos 5t - 2 \sin 5t)$$

$$= \frac{1}{29} \left(\frac{-10s + 50}{s^2 + 4} + \frac{10s + 10}{(s + 3)^2 + 25} \right)$$

Exercise 2. Solve the initial value problem

$$y^{(4)} + 2y'' + y = 4te^t; \quad y(0) = y'(0) = y''(0) = y^{(3)}(0) = 0.$$

$$\mathcal{L}\{y^{(4)} + 2y'' + y\} = \mathcal{L}\{4te^t\}$$

$$\frac{4}{(s-1)^2} = (s^4 + 2s^2 + 1)Y$$

$$Y = \frac{4}{(s-1)^2 (s^2 + 1)^2} = \frac{A}{(s-1)^2} + \frac{B}{s-1} + \frac{Cs + D}{(s^2 + 1)^2} + \frac{Es + F}{s^2 + 1}$$

$$\left(\begin{array}{l} A=1 \\ B=-2 \\ C=2 \\ D=0 \end{array} \quad \begin{array}{l} E=2 \\ F=1 \end{array} \right)$$

$$= \frac{1}{(s-1)^2} - \frac{2}{s-1} + \frac{2s}{(s^2 + 1)^2} + \frac{2s + 1}{s^2 + 1}$$

So
$$y = (t-2)e^t + (t+1)\sin t + 2\cos t.$$

Example 5. Solve the initial value problem

$$x'' + \omega_0^2 x = F_0 \sin \omega t; \quad x(0) = x'(0) = 0.$$

$$\mathcal{L}\{x'' + \omega_0^2 x\} = \mathcal{L}\{F_0 \sin \omega t\}$$

$$\frac{F_0 \omega}{s^2 + \omega^2} = s^2 X + \omega_0^2 X$$

$$X = \frac{F_0 \omega}{(s^2 + \omega^2)(s^2 + \omega_0^2)}.$$

If $\omega \neq \omega_0$,

$$X = \frac{F_0 \omega}{\omega^2 - \omega_0^2} \left(\frac{1}{s^2 + \omega_0^2} - \frac{1}{s^2 + \omega^2} \right)$$

and

$$X = \frac{F_0 \omega}{\omega^2 - \omega_0^2} \left(\frac{1}{\omega_0} \sin \omega_0 t - \frac{1}{\omega} \sin \omega t \right)$$

If $\omega = \omega_0$,

$$X = \frac{F_0 \omega_0}{(s^2 + \omega_0^2)^2}$$

and

$$X = \frac{F_0}{2\omega_0^2} (\sin \omega_0 t - \omega_0 t \cos \omega_0 t)$$

(Resonance)